Decision tables and case based reasoning

Zdzisław Pawlak

Institute for Theoretical and Applied Informatics Polish Academy of Sciences ul. Bałtycka 5, 44-100 Gliwice, Poland and Warsaw School of Information Technology ul. Newelska 6, 01-447 Warsaw, Poland e-mail: zpw@ii.pw.edu.pl

Abstract.

1 Introduction

2 Decision tables

Formally, by an *information system* we will understand a pair S = (U, A), where U and A, are finite, nonempty sets called the *universe*, and the set of *attributes*, respectively. With every attribute $a \in A$ we associate a set V_a of its *values*, called the *domain* of a. Any subset B of A determines a binary relation I(B) on U, called an *indiscernibility relation*, and defined as follows: $(x, y) \in I(B)$ if and only if a(x) = a(y) for every $a \in A$, where a(x) denotes the value of attribute a for element x.

Obviously I(B) is an equivalence relation. The family of all equivalence classes of I(B), i.e., a partition determined by B, will be denoted by U/I(B), or simply by U/B. An equivalence class of I(B), i.e., block of the partition U/B, containing x will be denoted by B(x).

If (x, y) belongs to I(B), we will say that x and y are B-*indiscernible* (*indiscernible with respect to* B). Equivalence classes of the relation I(B) (or blocks of the partition U/B) are referred to as B-*elementary sets* or B-granules.

If we distinguish in an information system two disjoint classes of attributes, called *condition* and *decision attributes*, respectively, then the system will be called a *decision system*, denoted by S = (U, C, D), where C and D are disjoint sets of condition and decision attributes, respectively.

An example of a decision table is shown in Table 1.

 Table 1. Decision table

case	disease	age	test	support
1	yes	old	+	320
2	yes	old	_	130
3	yes	middle	+	70
4	yes	middle		50
5	yes	young	-	30
6	no	old	+	80
7	no	old	-	40
8	no	young	_	280

In the table 8 cases of patients stuffering from a certain disease, together with test result is presented. In the table the number of cases of every "type" of patients is given and is called *support* of the type. *Disease* and *age* are condition attributes, whereas *test* is condition attribute.

Every row (case) in the decision table determine a decision rule. For example, row 3 determines a decision rule

if (disease, yes) and (age, middle) then (test, +).

Normalized support for a decision rule will be called *strength* of the decision rule. For example, strength of the above decision rule is 70/1000 = 0.07.

With every decision table we associate a decision graph $G = (N, B, \sigma), B \subseteq N \times N$, where N is a set of *nodes* B set of *branches* (pair of notes) and σ is the strength of the branch. Nodes represent conditions and decision of the decision table, whereas branches represents decision rules.

With every branch (decision rules) (x, y) of a flow graph G we associate the *certainty factor*

$$\operatorname{cer}(\mathbf{x}, \mathbf{y}) = \frac{\sigma(\mathbf{x}, \mathbf{y})}{\sigma(\mathbf{x})}$$

and the coverage factor

$$cov(x, y) = \frac{\sigma(x, y)}{\sigma(y)}$$

where $\sigma(x) \neq 0$ and $\sigma(y) \neq 0$.

These coefficients are widely used in data mining (see, e.g., [5,11,12]) but they can be traced back to Łukasiewicz [4], who used them first in connection with his research on logic and probability.

3 Properties of decision rules

The following properties are immediate consequences of definitions given above:

$$\sum_{\mathbf{y}\in\mathbf{O}(\mathbf{x})}\operatorname{cer}(\mathbf{x},\mathbf{y}) = 1 \tag{1}$$

$$\sum_{\mathbf{x}\in I(\mathbf{y})} \operatorname{cov}(\mathbf{x}, \mathbf{y}) = 1 \tag{2}$$

$$\sigma(\mathbf{x}) = \sum_{\mathbf{y} \in \mathcal{O}(\mathbf{x})} \operatorname{cer}(\mathbf{x}, \mathbf{y}) \sigma(\mathbf{x}) = \sum_{\mathbf{y} \in \mathcal{O}(\mathbf{x})} \sigma(\mathbf{x}, \mathbf{y})$$
(3)

$$\sigma(\mathbf{y}) = \sum_{\mathbf{x} \in \mathbf{I}(\mathbf{y})} \operatorname{cov}(\mathbf{x}, \mathbf{y}) \sigma(\mathbf{y}) = \sum_{\mathbf{x} \in \mathbf{I}(\mathbf{y})} \sigma(\mathbf{x}, \mathbf{y})$$
(4)

$$\operatorname{cer}(\mathbf{x}, \mathbf{y}) = \frac{\operatorname{cov}(\mathbf{x}, \mathbf{y})\sigma(\mathbf{y})}{\sigma(\mathbf{x})}$$
(5)

$$cov(\mathbf{x}, \mathbf{y}) = \frac{cer(\mathbf{x}, \mathbf{y})\sigma(\mathbf{x})}{\sigma(\mathbf{y})}$$
(6)

The above properties have a probabilistic flavor, e.g., equations (3) and (4) have a form of total probability theorem, whereas formulas (5) and (6) are Bayes' rules [10]. However, in our approach, these properties are interpreted in a deterministic way and they describe flow distribution among branches in the network.

Decision graph associated with Table 1 is given in Fig. 1.



Fig. 1. tytul

4 Dependencies in decision tables

Let x and y be nodes in a decision graph $G = (N, \mathcal{B}, \sigma)$, such that $(x, y) \in \mathcal{B}$. Nodes x and y are *independent* in G if

$$\sigma(x,y) = \sigma(x)\sigma(y). \tag{7}$$

From (7) we get

$$\frac{\sigma(x,y)}{\sigma(x)} = cer(x,y) = \sigma(y), \tag{8}$$

and

$$\frac{\sigma(x,y)}{\sigma(y)} = cov(x,y) = \sigma(x).$$
(9)

If

$$cer(x,y) > \sigma(y),\tag{10}$$

$$cov(x,y) > \sigma(x),\tag{11}$$

x and y are *positively depends* on x in G. similarly, if

$$cer(x,y) < \sigma(y),\tag{12}$$

 or

$$cov(x,y) < \sigma(x),\tag{13}$$

then x and y are negatively dependent in G.

Relations of independency and dependences are symmetric ones, and are analogous to those used in statistics.